

Mission/SOW

Project Goal: Develop a high-quality training tool for rocket assembly and loading.

Project Parameters:

- Adjustable center of gravity
- Streamlined rocket body
- Weight range: 2300-2400 pounds
- Easy assembly by two people
- Electronic alignment sensor

Training Objectives:

- Rocket assembly using current transport vehicle
- Loading procedures from RTV to launch rail

Rail Alignment System (D.WOBBLER):

- Keeps the rocket aligned with the launch rail
- Lowers misalignment risk during training

Research

Black-Oxide Alloy Steel Hex Drive Flat Head Screw 1/2"-20 Thread Size, 1-1/2" Long

■ Tensile Strength: 130,000 psi

Hardness: Rockwell C39

Quikrete 80lb Concrete Mix

- High-Strength 4000 psi concrete
- Meets ASTM C 387 compressive strength requirements

Carbon Steel

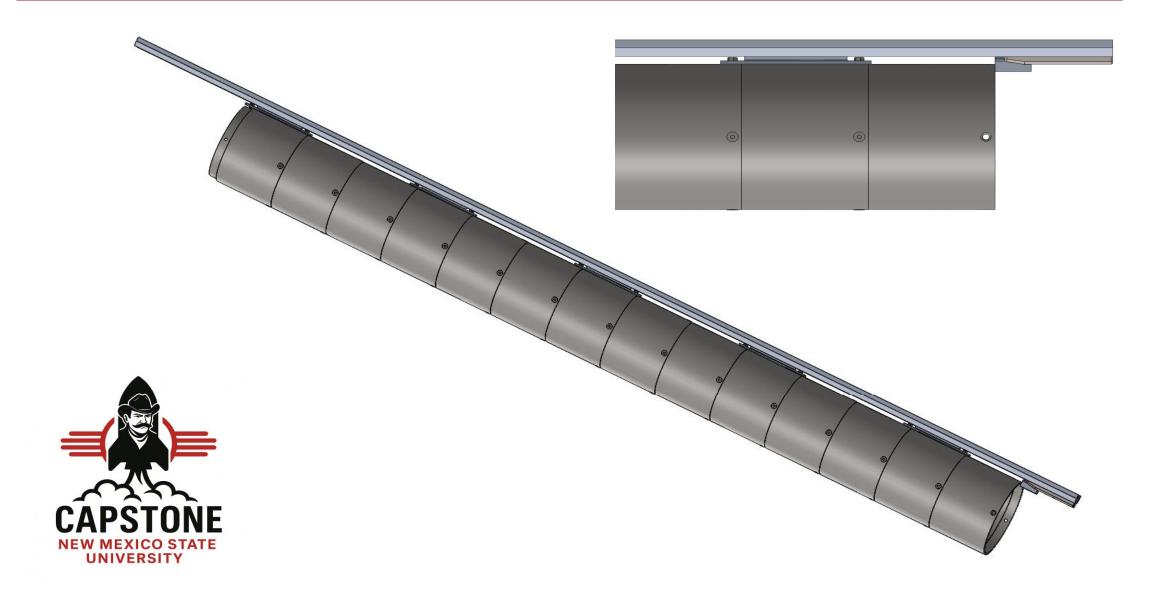
- Tensile Strength: 60200 psi
- Hardness: Rockwell B84

Black Brant IX

- CG is generally located at the midpoint of the body
- Empty weight: 1,980 lbs

Electronics (Arduino)

- 9 DoF IMU with Arduino & ESP32 Development
 kit
- 9V battery holder
- Will detect any tilt, movement, and coordinates



Design and Fabrication of a Mockup Rocket for NMSA

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Final Design



Final Design:

(1) Mockup Rocket Shell:

- 14" OD x 12.75" ID Carbon Steel Tubing
- Each section weighs roughly 80 lbs and is 12 inches long
- A step was incorporated to ensure tubes will sit evenly on one another
- No additional holes are needed for rail guides, as they can be installed using the existing countersunk holes

(2) Rail Alignment System (D.WOBBLER):

- Accelerometer, Magnetometer, Gyroscope
- Leveled with surface and magnetic poles
- Detection of angular velocity & displacement
- Bluetooth compatibility

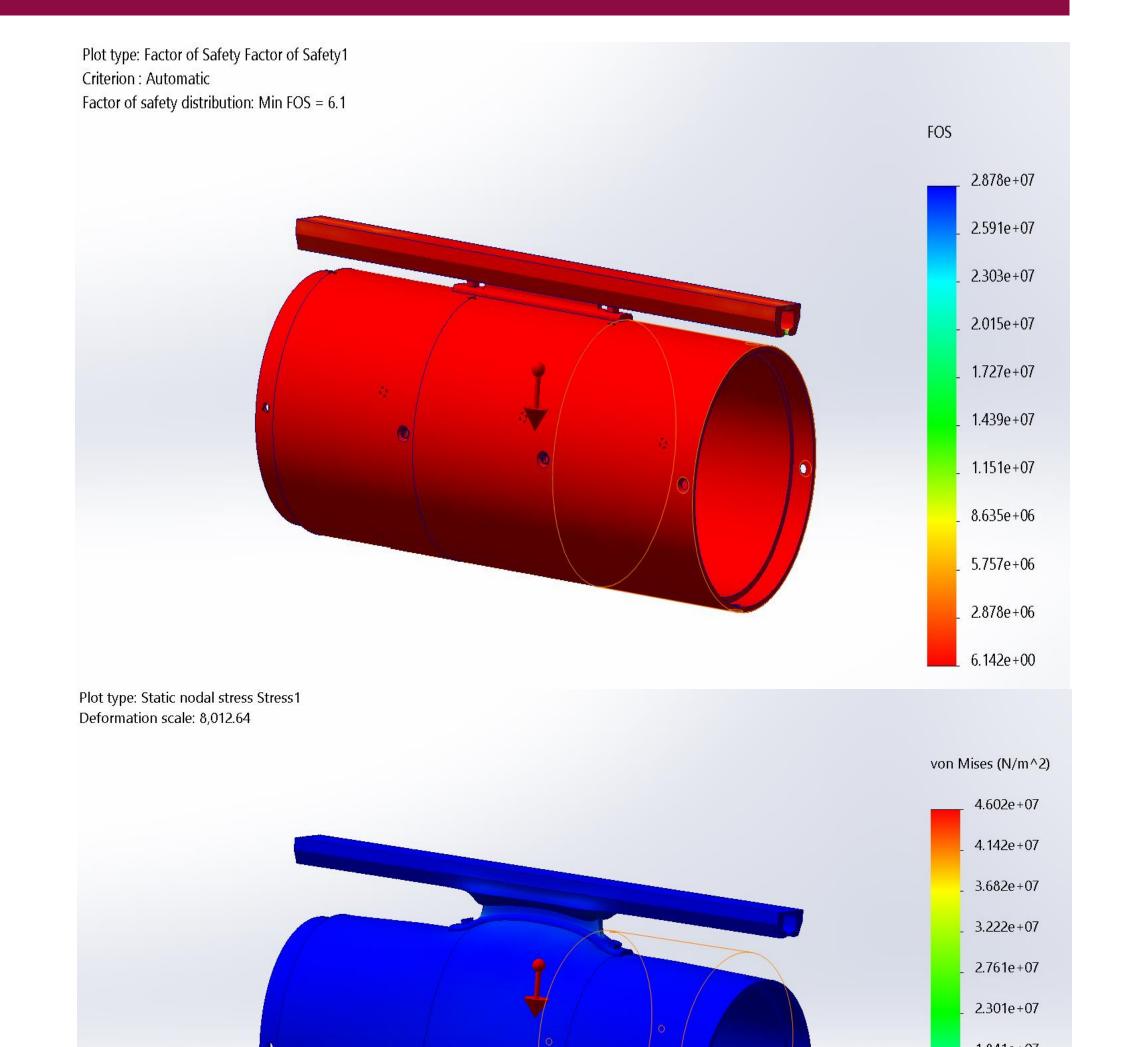
(3) Rail Guides:

- Attach directly to pre-existing countersunk holes
- Designed to hold 600 lbs each
- Light weight yet durable

(4) Concrete Weights:

- Total of 28 weights
- Each weighing from 38-41 lbs
- Designed to be easily moveable by one person and meet weight requirements

Total Project Cost: \$9,761



Rail Alignment System (D.WOBBLER) Design Phase:

Objectives

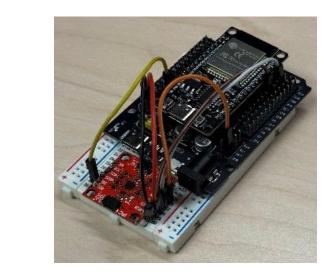
- Read and transmit coordinates
 - 1. X, Y, Z position & acceleration
- Position to desired path
- Predict landing through coordinates
 - 2. Predict State Vector in 3D Space
- Easy to assemble and troubleshoot

Preliminary Design:

- Weatherproof
- Aligned with rail
- Compacted and mounted
- Simple circuit
- Simple one-dimension reading
- Specific orientation

Design Concept

- Round and screw-in top
- Flat surface to mount on rail
- Screw-in to hole on top of rail
- Internal mount for Wobbler system









1.381e+07

9.204e+06



Concept Development

Mockup Rocket Shell

Design Phase:

Objectives

- No more than 90 lbs a piece
- Maneuverability
- High Strength
- Easy to machine

Preliminary Design:

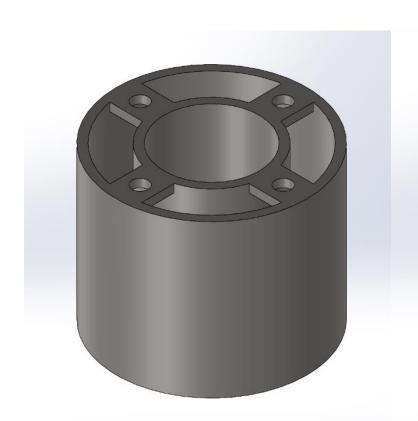
- Cylindrical body to mimic rocket shape
- Simple assembly
- Meets weight requirements
- Too much material needed
- Poor machinability

Design concepts considered: Concept 1

- 12" OD x 0.25" Wall
- Pros:
 - 1. Met weight requirement with concrete weights
- 2. Aligned the sections well to prevent shifting
- Cons:
 - 1. Required more machined parts
 - 2. Would require welding

Concept 2

- 10.75" OD x 0.365" Wall
- Pros:
- 1. Smaller/Lighter easy to handle
- 2. Appropriate size to be machined in house
- Cons:
- 1. Required more material
- 2. 25+ pieces would need to be machined





References

- Black Brant v Launch Vehicle (21.XXX), sites.wff.nasa.gov/code810/vehicles/Black_Brant_V.pdf. Accessed 10 Feb. 2025.
- https://forum.arduino.cc/
- Carbon Steel Round tubing. Carbon Steel Round Tubing | Carbon Steel | Totten Tubes. (n.d.).